## WAAS navigation: IFR operations review

Brian Eliot, CFI San Carlos Flight Center

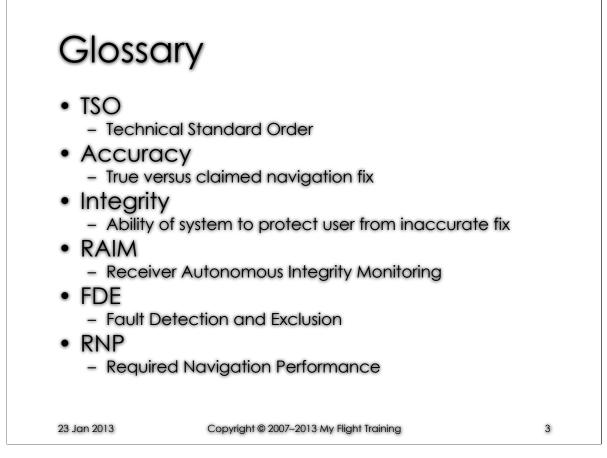
## Agenda

- WAAS overview
- Pre-WAAS IFR navigation
- Post-WAAS IFR navigation
- Approach design principles
- WAAS equipment
- Charting and procedures
- Regulations

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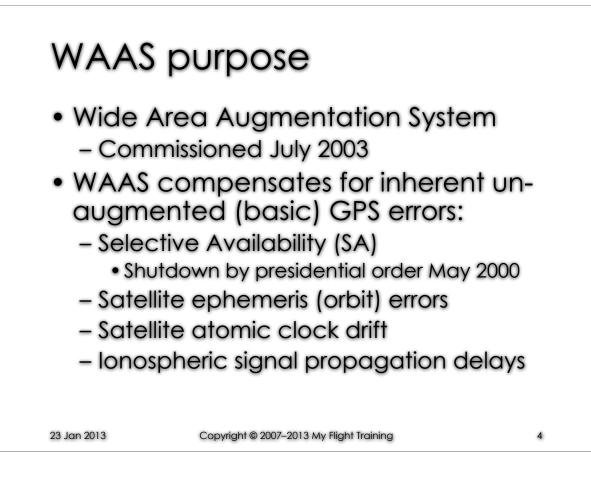
•Accuracy is the difference between the corrected navigation fix and the true position.

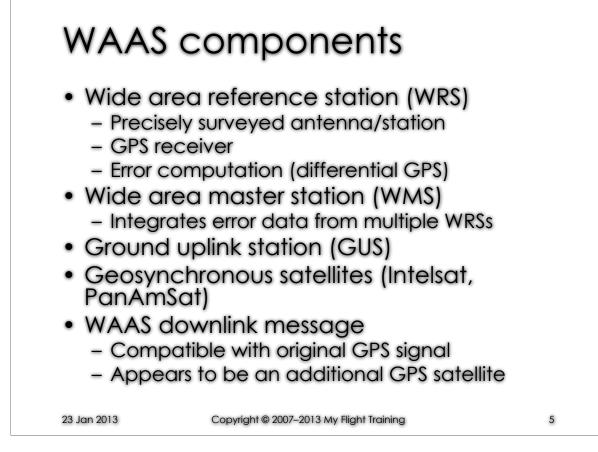
•Accuracy or more specifically, Navigation Sensor Error (NSE) is defined as the difference between the position estimated by the navigation sensor and the true position of the aircraft which is only exceeded 5% of the time in the absence of system failures.

•Integrity measures the ability of the system to protect the user from inaccurate position estimates in a timely fashion.

•Continuity measures the navigation system's ability to complete an operation without raising an alarm.

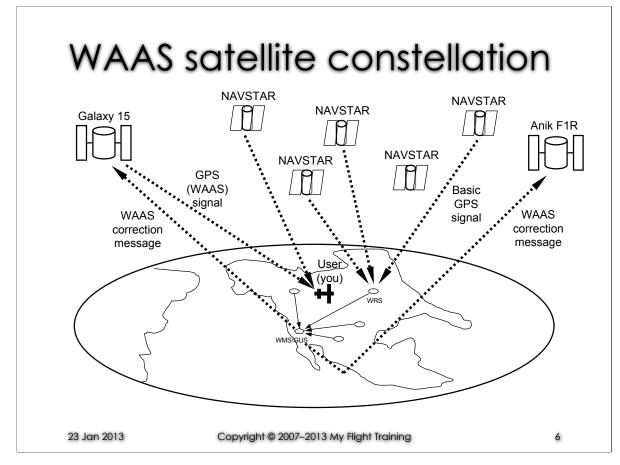
•Availability is computed as the fraction of time the WAAS system is providing position fixes to the specified level of accuracy, integrity and continuity.





## •WAAS dowlink messages

- •Fast
- •Relative to position of user (receiver)
- •Different receivers see different effects/satellites
- Ionospheric map
- Slow
- Global to all users
- •Ephemeris
- •Clock drift



•NAVSTAR is the original (Block I) GPS implementation. Block IIIC is the latest.

•24 required to meet design performance

•31 actually operational in orbit

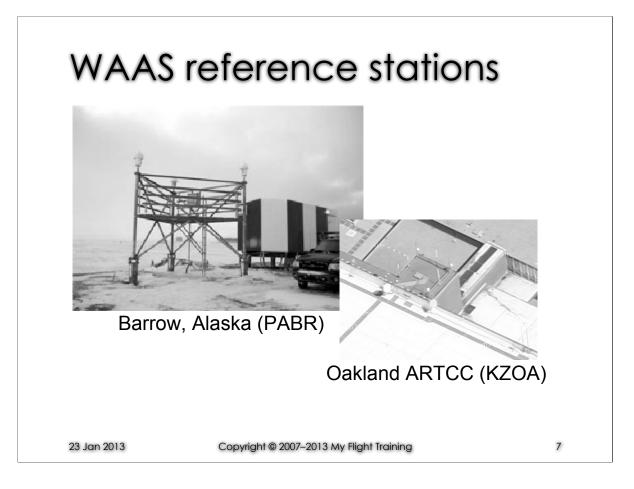
•Later improved Blocks were launched under a variety of satellite names.

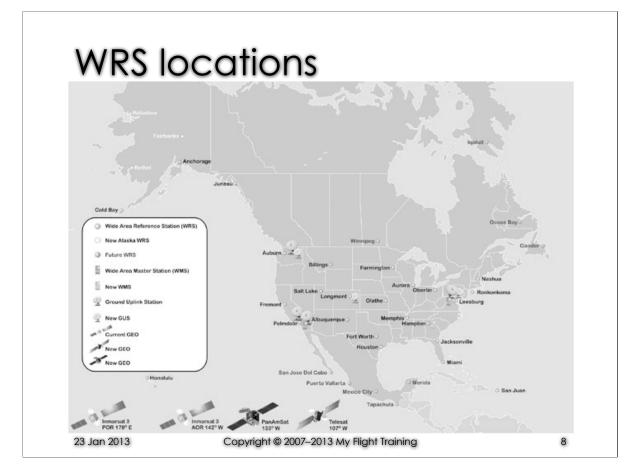
•WAAS is available only in North America by virtue of WRS distribution and geostationary satellite coverage.

•Other parts of the world are implementing their own GNSS and differential correction constellations.

•The WAAS receiver picks up both basic GPS signals from the GPS satellites and WAAS correction messages from the geosynchronous satellites.

•There is a west and an east geosynchronous satellite.



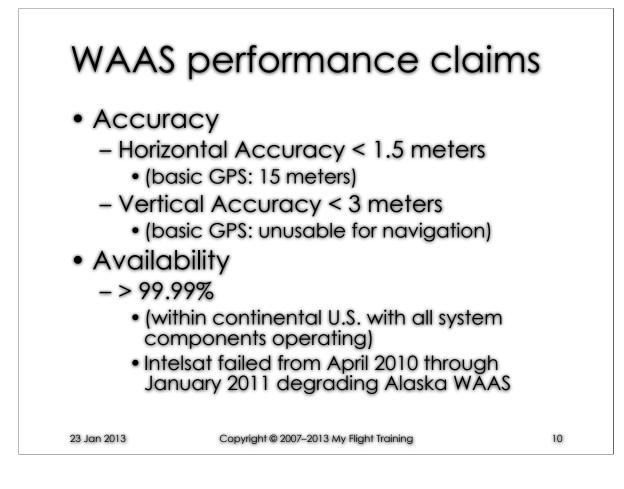


The distribution of WRSs makes it clear why WAAS service is available only in North America.

WAAS	versus basic GPS	
– Horizo – Vertic	ed and more useable accuracy ntal (LNAV) al (VNAV) ed availability	
	ased susceptibility to satellite outage	
	ed integrity	
	immediate fault detection	
– Specif	ied maximum alarm delay	
- Measu	urable quality of service	
– Real-ti	ime satellite monitoring and exclusion	
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•Horizontal Alarm Limit (HAL)

•Vertical Alarm Limit (VAL)





•TSO is Technical Standard Order

•TSO C-129 covered approach-certified aviation GPS beginning in the 1990s

Examples

•Garmin GNS430, GNS530

•UPS AT (Garmin) GX60

•Bendix/King KLN89B, KLN90B, KLN94

•Trimble 2000 Approach

•TSO C-145 is FMS with WAAS

•TSO C-146a

•Examples

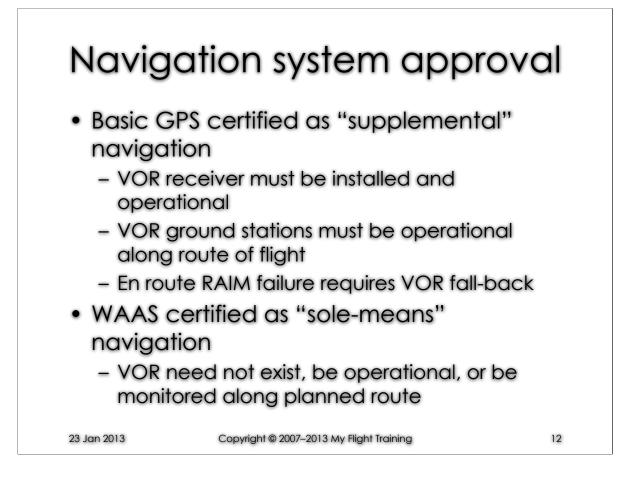
•Garmin GTN750, GTN650, GNS430W, GNS530W, GNS480

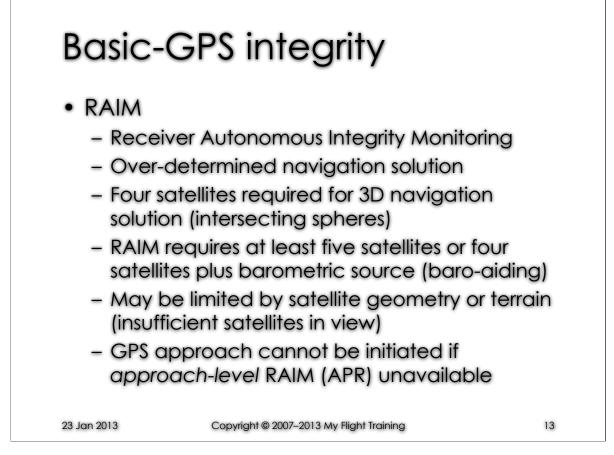
•Garmin G1000 (with WAAS hardware and software)

•UPS AT (Garmin) CNX80

•TSO C-146b

•TSO C-146c (current)



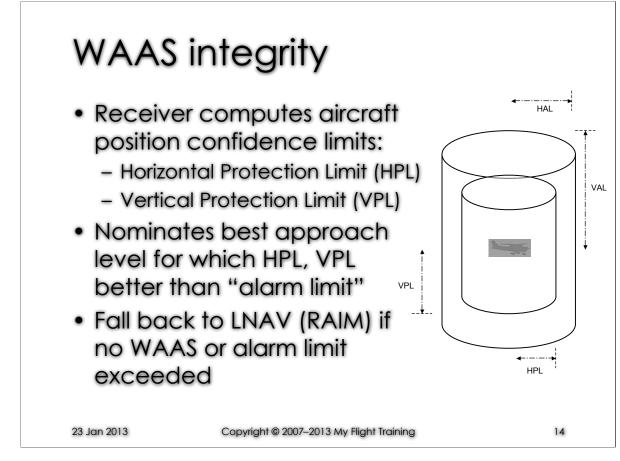


•GPS satellites, contrary to popular belief, are not in geosynchronous orbits. They are in 12-hour orbits so a given satellite appears to rise and set.

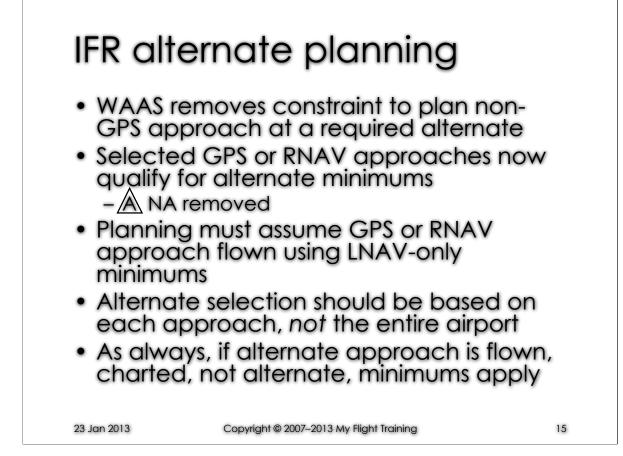
•The operational GPS constellation of 24 satellites is designed so that the minimum number of satellites to compute a position is in view everywhere on earth.

•RAIM is always operating. Its level of accuracy changes depending on the phase of flight and the immediate level of accuracy is displayed by the GPS navigator (e.g., TERM).

•The levels of RAIM accuracy are OCN, ENR, TERM, and APR.



lonospheric propagation delay is the largest single contributor to basic GPS inaccuracy.



•GPS alternate planning required assumption that GPS is unavailable at the alternate.

•GPS approach cannot be planned at alternate

•GPS substitution for DME or ADF on a conventional approach cannot be planned at alternate

•All GPS approaches were marked "not authorized" (NA) for alternate minimums.

•On NACO plates, NA legend is in the notes block

•On Jeppesen plates, alternate minimums are tabulated at the bottom of the airport page.

•WAAS alternate planning should examine each approach at the planned alternate, not the airport as a whole.

•Some GPS and RNAV (GPS) approaches now have the NA legend removed, and they are available as alternate candidates.

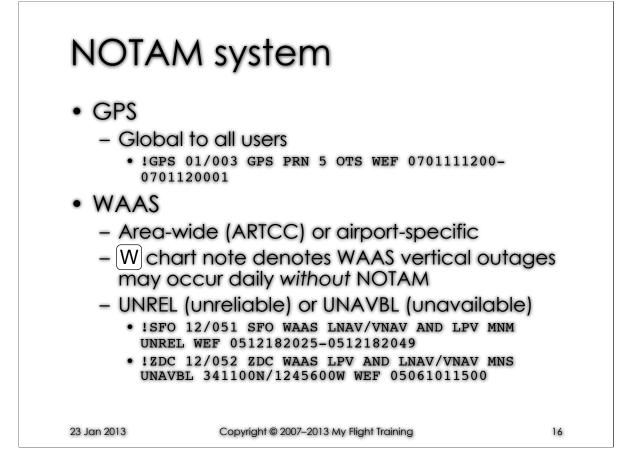
•The reverse-A legend may still appear. It means alternate minimums for this approach are non-standard. Check the appropriate section of the TPP.

•For Jeppesen, check the alternate minimums tabulation. Under WAAS, GPS and RNAV (GPS) approaches may be listed there.

•For planning purposes, the approach must assume lateral navigation (LNAV) minimums only. Vertical navigation must be assumed to be out--of-tolerance.

•This means that RNAV (GPS) approaches with LPV minimums only cannot be considered.

•As always, minimums consideration is for planning prior to departure only. Upon proceeding to any alternate and flying an approach, the actual published minimums, including vertical navigation minimums, apply.



•WAAS and GPS outages are reported by NOTAM.

•GPS outages are reported for location identifier GPS.

•GPS satellite outages are reported by PRN, or "pseudo-random number," which effectively is the number of the satellite.

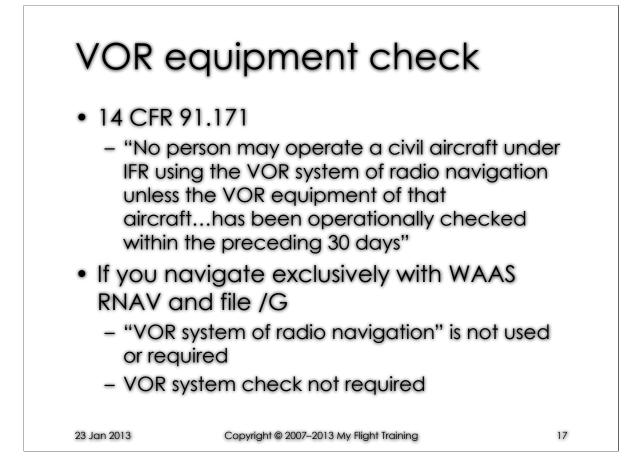
•WAAS NOTAMs are issued

•by specific location identifier for large terminals.

•by ARTCC location identifier for wide areas and for terminals not covered by specific NOTAMs.

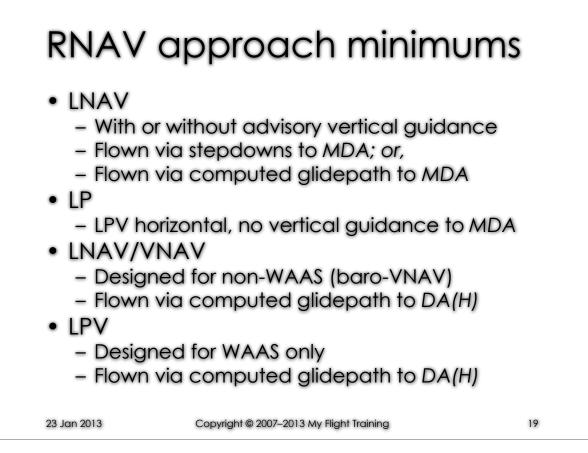
•Oakland Center location identifier is ZOA

•On NACO charts, reverse-W symbol in notes block denotes that site-specific NOTAMs for this airport are not issued



	approach classifica	
<ul> <li>Non-pressure</li> </ul>		
– No ve	rtical guidance	
<ul> <li>Precisic</li> </ul>	n	
– Glidej	path deviation	
– ILS, M	ls, par, gls	
	ach with Vertical Guidance ( bath deviation	APV)
	meeting precision standards of ICAO An	nex 10''
	/VNAV, LPV, LDA/GS	
	ment presentation same as "prec	ision"
	ies as "precision" per Jan. 2010 IF	
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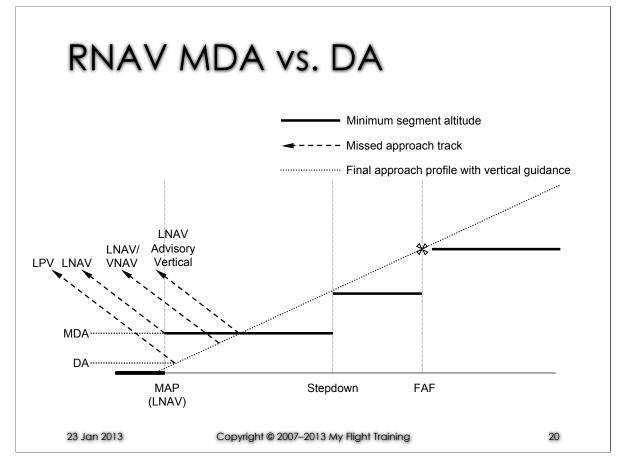
- APV is classified as a new kind of vertical guidance instrument approach
  - Technically not considered a "precision" approach
    - Not meeting ICAO Annex 10 standards
  - From pilot perspective, flown identically to precision approach with same navigation presentation and flown to a DA(H), not MDA
- Instrument Rating practical test standard (PTS) published January 2010
  - APV approaches qualify as meeting the requirement to perform a "precision" approach
  - · Applicable to instrument rating practical test
  - Applicable to instrument proficiency check (IPC)
- AIM 5-4-5(a)(7)
  - (a) Precision Approach (PA). An instrument approach based on a navigation system that provides course and glidepath deviation information meeting the precision standards of ICAO Annex 10. For example, PAR, ILS, and GLS are precision approaches.
  - (b) Approach with Vertical Guidance (APV). An instrument approach based on a navigation system that is not required to meet the precision approach standards of ICAO Annex 10 but provides course and glidepath deviation information. For example, Baro-VNAV, LDA with glidepath, LNAV/VNAV and LPV are APV approaches.
  - (c) Nonprecision Approach (NPA). An instrument approach based on a navigation system which provides course deviation information, but no glidepath deviation information. For example, VOR, NDB and LNAV. As noted in subparagraph h, Vertical Descent Angle (VDA) on Nonprecision Approaches, some approach procedures may provide a Vertical Descent Angle as an aid in flying a stabilized approach, without requiring its use in order to fly the procedure. This does not make the approach an APV procedure, since it must still be flown to an MDA and has not been evaluated with a glidepath.



•These are the charted minimum lines titles

•LP was added later

- •It may not be supported by the software in some earlier WAAS receivers
- •It offers LPV horizontal accuracy, but does not provide vertical guidance
- •Usually due to surrounding terrain
- •Same relationship between LPV/LP as ILS/LOC
- •LPV normally offers 250 HAT DH
- •LPV-200 offers 200 HAT DH



•Vertical guidance approaches flown to DA(H)

•They may not be "precision" approaches despite having vertical guidance •Non-vertical guidance approaches flown to MDA

•Required Obstacle Clearance (ROC)

•Is a sloping surface for vertical guidance approaches

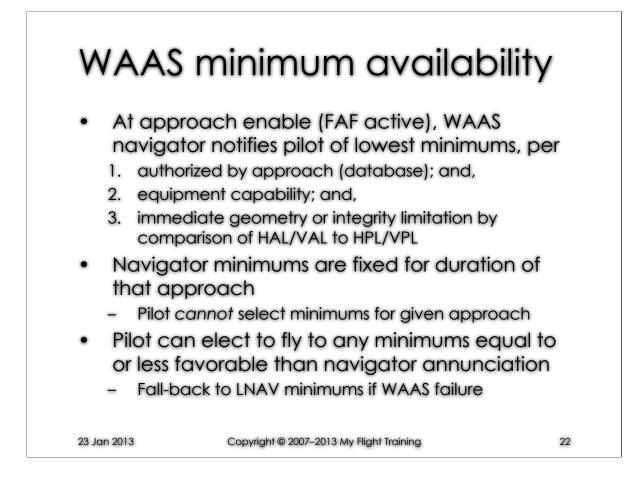
•Is a flat surface between fixes for "dive-and-drive" approaches

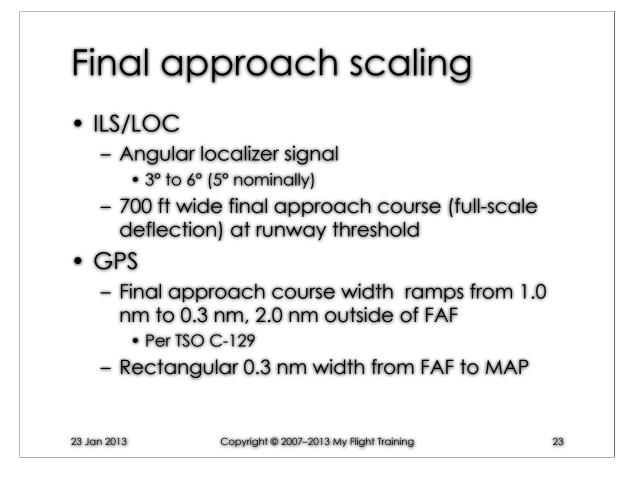
•Differing Obstacle Clearance Surface (OCS) shapes sweep up different obstacles, resulting in different MDA or DA

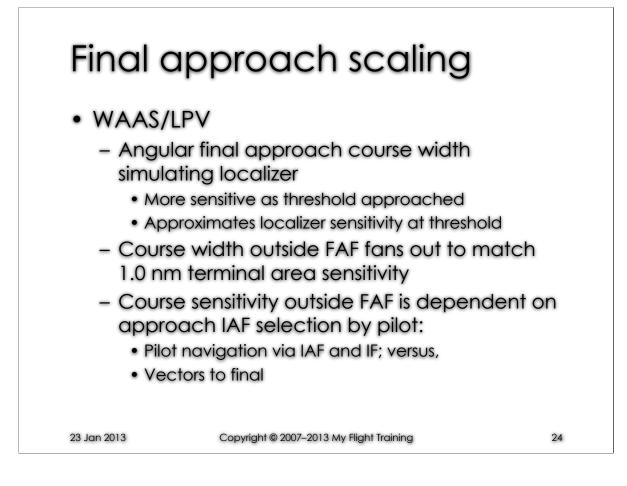
•Guideslope Qualification Surface (GQS) governs vertically-guided approaches

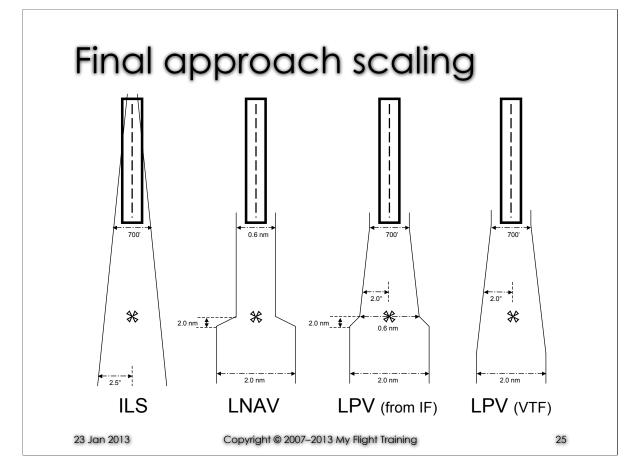
•Close-in obstacles may penalize a vertical guidance approach (GQS) where an approach with an MDA would not be affected

See TERPS for details









Splay computations

•2.0°

•350' at threshold (10022 ft) from origin

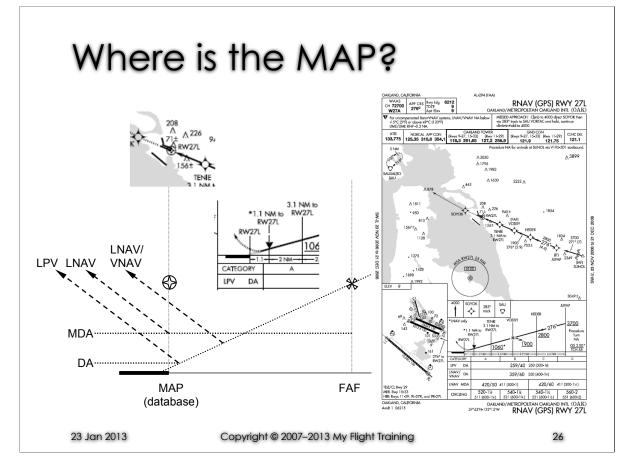
- •0.3 nm at 6.94 nm (42140 ft) from threshold
- •1.0 nm at 27 nm (163856 ft) from threshold

•2.5°

•350' at threshold

•0.3 nm at 5.55 nm (33732 ft) from treshold

•1.0 nm at 22 nm (131055 ft) from threshold



•On the glideslope at barometric minimum for precision/APV

•LNAV/VNAV

•LPV

•At the published (database) MAP for LNAV

•What about the chart?

## •NACO

•NACO charts show transition from solid to dashed procedure track at lowest precision minimum

•FAF-to-MAP table not included for RNAV approach

•Plan view shows miniaturized fly-over waypoint symbol for LNAV MAP

Profile view show LNAV MAP

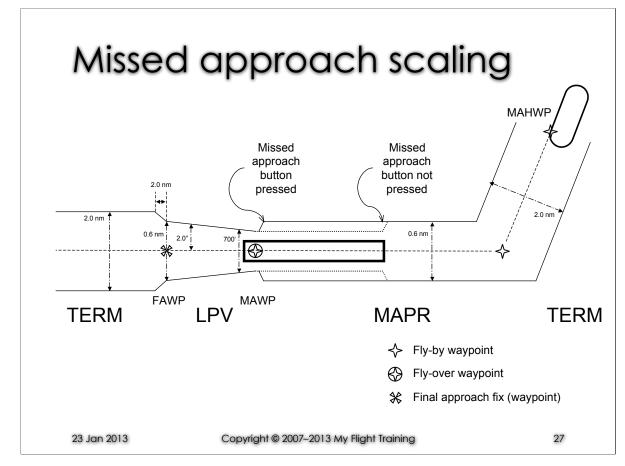
•Study and know Aeronautical Chart User's Guide!

•There are many different ways that the MAP can be depicted, depending on the type of approach. On all approach charts it is depicted in the profile and planviews by the end of the solid course line and the beginning of the dotted missed approach course line for the top-line/lowest published minima. For a precision approach, the MAP is the point at which the aircraft reaches the DA or DH while on the glide slope. On some nonprecision approaches, the MAP is given as a fixed distance with an associated time from the FAF to the MAP based on the groundspeed of the aircraft. A table on the lower right hand side of the approach chart shows the distance in NM from the FAF to the MAP and the time it takes at specific groundspeeds, given in 30- knot increments.

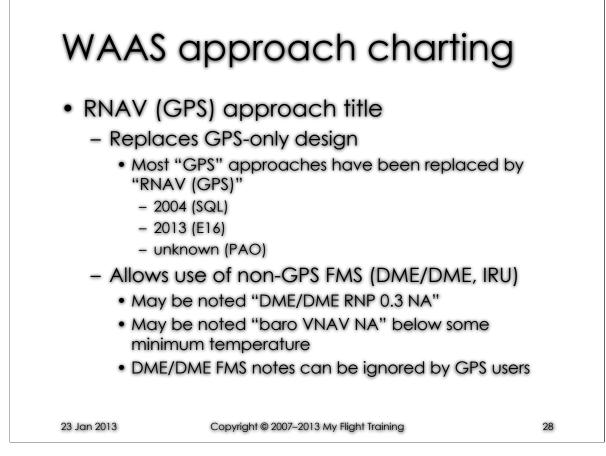
•Jeppesen charts are clearer

•Show missed approach track profile for each minimum

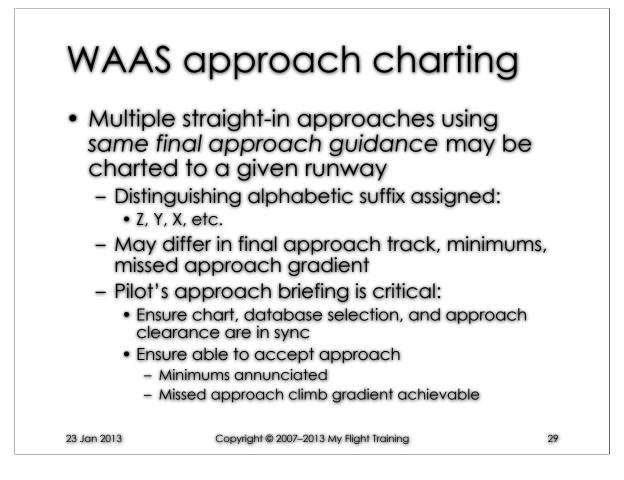
•Don't fly to database MAP on a VNAV profile!



- •TERM to IF or when FAWP becomes active
- •LPV after IF or FAWP active
- •MAPR at MAWP with straight-ahead missed
- •TERM at first turning fix after MAWP



Non-overlay GPS and RNAV (LNAV) approaches are designed to the same criteria.



		•	<u> </u>	h ch			
	e Path Indicator AS) way)	WAAS CH <b>72700</b> W27A		CALCADA CAUTORIA CH 722700 APT CS [hop 16] W27A 200 PAT CS [hop 16] W27A 200 PAT CS [hop 16] W27A 200 PAT CS [hop 16] HIG (SP) 0004 47C (1207) DR/C/MR CR <sup>3</sup> 0.3 NA ATIS INCICAL APC CON 133.775 [125,35 310.8 364. SAUSA	9 OAKL terrs, UNAV/VNAV NA below OAKLAND TOWER OAKLAND TOWER (Rwys 9-27, 15-33) (Rwy 11 118,3 291,65 127,2 2	56.9 121.9 121.75 dure NA for arrivals at SUNOL via V195	INTL (OAE ct SOYOK fren confinue ) CINC DEL 121.1
	Glideslope angle d crossing height	Turn NA <u>GS 3.00</u> TCH 55		A 181 - 550 - 60 - 100 -	208 А 224 SOYOK 1567 1567 1567		334 3700 A 271* (7) - 2349 2349 SUNC 3049±A
VAAS Minimun	ns ; DA replaces DH)	-1- 4.71		6 A 100 6 A 100 A 100 101 101 101 101 101 101 101	4000 SOYOK 283* trock *UNAV orly *UNAV	VODSY HEDER	3700 Procedure Ture NA
CATEGORY	A	В	T	161 /	CATEGORY A	60* 1700 26 NM 239 NM 4.6 NM B C	GS 3.00 TCH 35 D
LPV DA	1	259/40	2	Server Server	LINAV/ DA VINAV/ DA	259/40 250 (300-34) 359/60 350 (400-14)	
LNAV/ DA		359/60	3	TDZ/CL Rwy 29 MRI Rwy 15:33 HIRL <u>Swp</u> 11:29, 91-27R, and 98-27L OAKLAND, CALIFORNIA	CIRCUNG 520-1% 511 (600-1%)	411 (500-1) 420/60 4 540-1)( 540-1)( 531 (600-1)() 531 (600-1)() AND/METROPOLITAN OAKLAND	560-2 551 (600-2)

•WAAS data block

•"WAAS"

•Channel number (five digits)

•Reference Path Indicator

•W

•Runway numeric designator

•A, B, C, etc. per ICAO standards surroages for L, C, R

•WAAS minimums

•Up to four lines

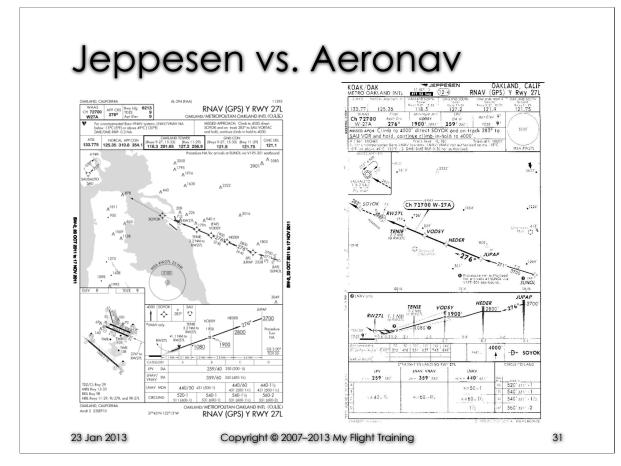
•LPV

•LNAV/VNAV

•LNAV

•Circling

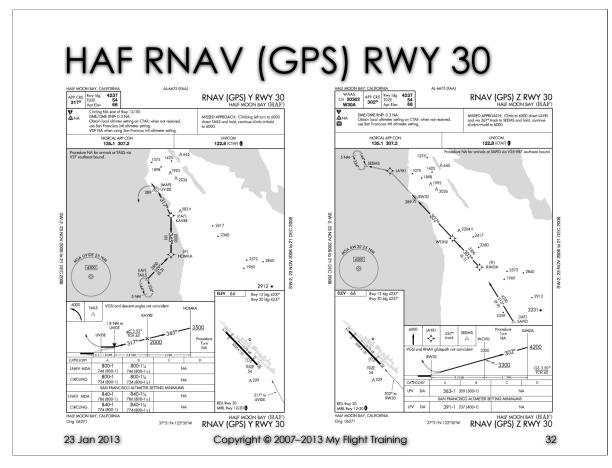
•GLS or GLS-PA lines have been removed



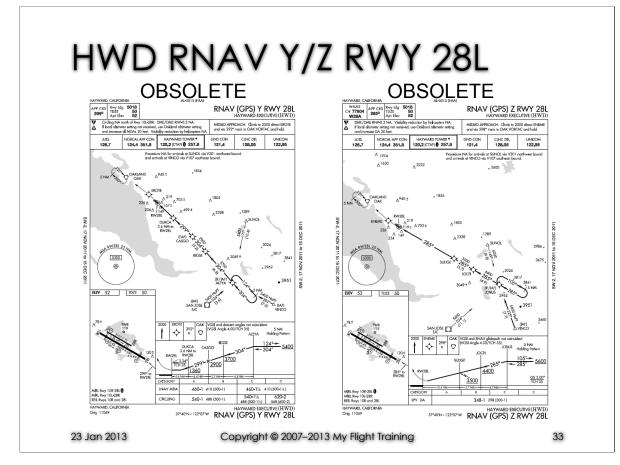
•Minimums layout

•Timing table (Jeppesen only)

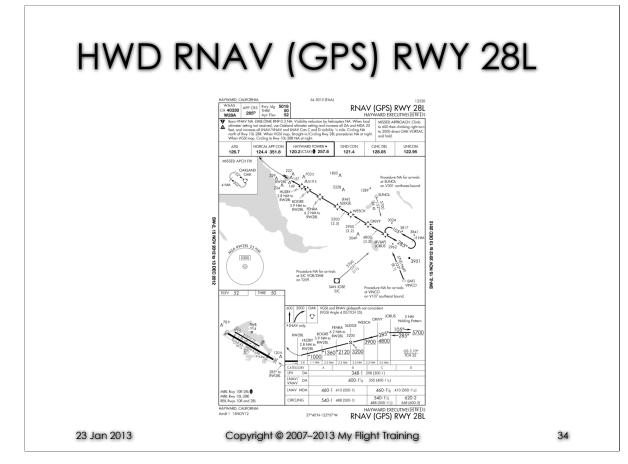
- •Vertical descent angle
- •Rate of descent tabulation
- Missed approach symbols
  - •Jeppesen
    - •M for LNAV MAP
    - •Upward-turning arrows for each APV missed
  - Aeronav
    - •LNAV MAP marked with undistinguished fix (usually at threshold)
    - •Lowest minimums MAP transitions to dotted line in profile view



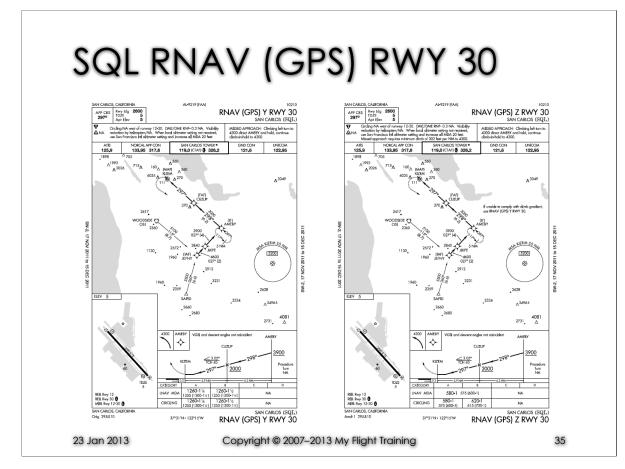
- •Different final approach tracks
- Separate minimums
- •LPV chart has no circling minimums
- •LPV approach has straight-ahead missed (MAPR)



- •Different final approach tracks
- •LPV aligned with runway heading
- •LPV chart has no circling minimums



- •Different final approach tracks
- •LPV aligned with runway heading
- •LPV chart has no circling minimums



- •Identical final approach tracks
- Identical approach fixes
- •Identical minimums labels

•Approaches differ only in non-standard missed-approach climb gradient, which necessitates different MDAs

ls my G	PS WAAS-capable	eş
- GPS400 - GPS500	FD540	
<ul> <li>Check sto</li> </ul>	artup screen and config pa	ges
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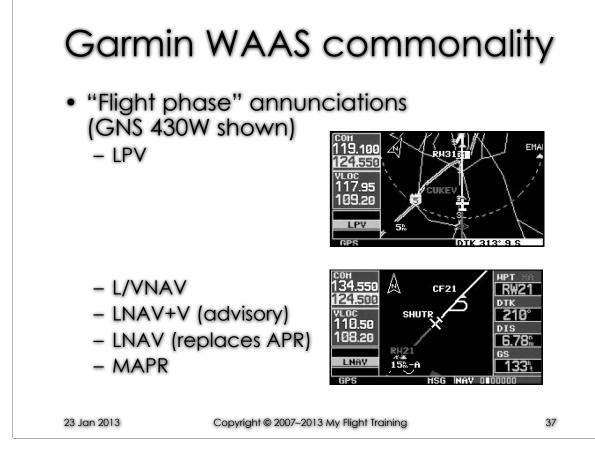
On some equipment, WAAS is an option, and presence cannot be detected by equipment model number

- •Check startup screen
- •Check satellite status pages
- Check config pages

•SBAS turned ON/OFF

- •MSAS turned ON/OFF
- •RNAV approaches available for selection

•Approaches in database but not available due to equipment are showed grayed out



Approach level annunciations have changed

•APR is gone

•Level of WAAS horizontal/vertical accuracy is now annunciated as

- •LNAV
- •LNAV+V (LNAV with advisory vertical guidance)
- •L/VNAV
- •LP
- •LPV
- •LNAV is annunciated for conventional navaid (e.g., LOC) approaches
- •MAPR is for missed approach guidance on straight-ahead misses (like LPV)

